

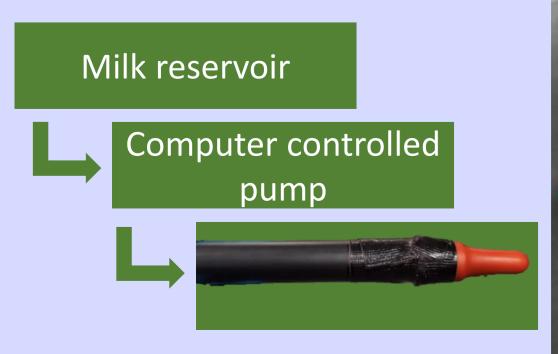
Background

- One of the main challenges of infant feeding is generating enough suction to acquire milk¹.
- Sensory stimulation during milk acquisition impacts feeding physiology during transport and swallowing².
- How does automated milk delivery impact infant sucking and swallowing kinematics?



Methods

- Surgically implanted radiopaque markers into the tongue and hyoid.
- Filmed infant pigs using biplanar videofluoroscopy when feeding on a bottle and with automated milk delivery².
- Data was processed using XMALab and MAYA.



The impact of automated milk delivery on infant feeding performance Steer KE¹, Adjerid K¹, Bond LE¹, Edmonds CE¹, German RZ¹, Gould FDH², Mayerl CJ¹

¹Department of Anatomy and Neurobiology, Northeast Ohio Medical University ²Department of Cell Biology and Neuroscience, Rowan School of Osteopathic Medicine



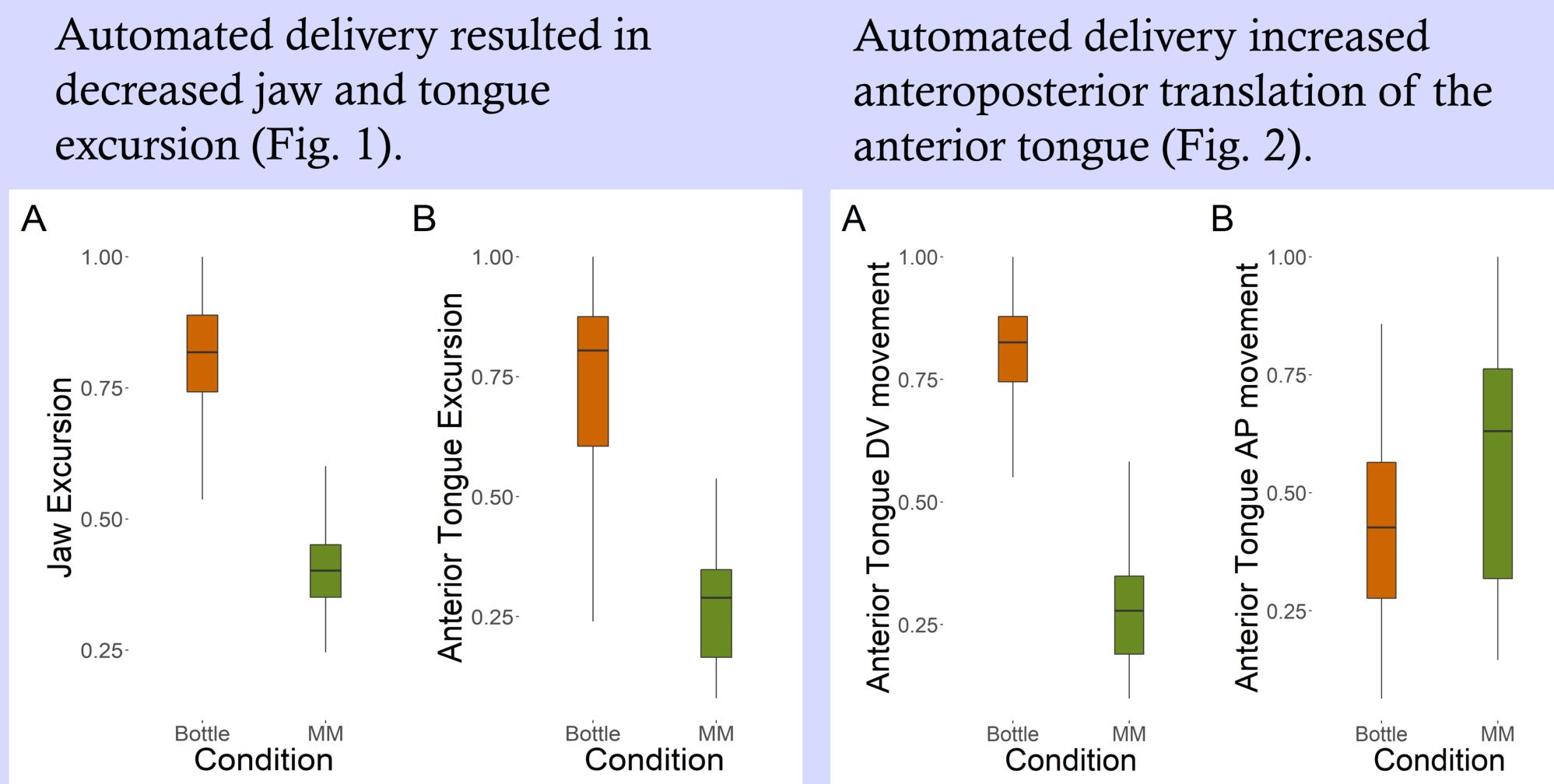


Figure 1. Boxplots showing differences in scaled jaw (A) and anterior tongue (B) total translation. Automated delivery resulted in drastically decreased total translation of both.

Bolus size was larger when pigs fed on automated milk delivery system than when bottle feeding (Fig. 3).

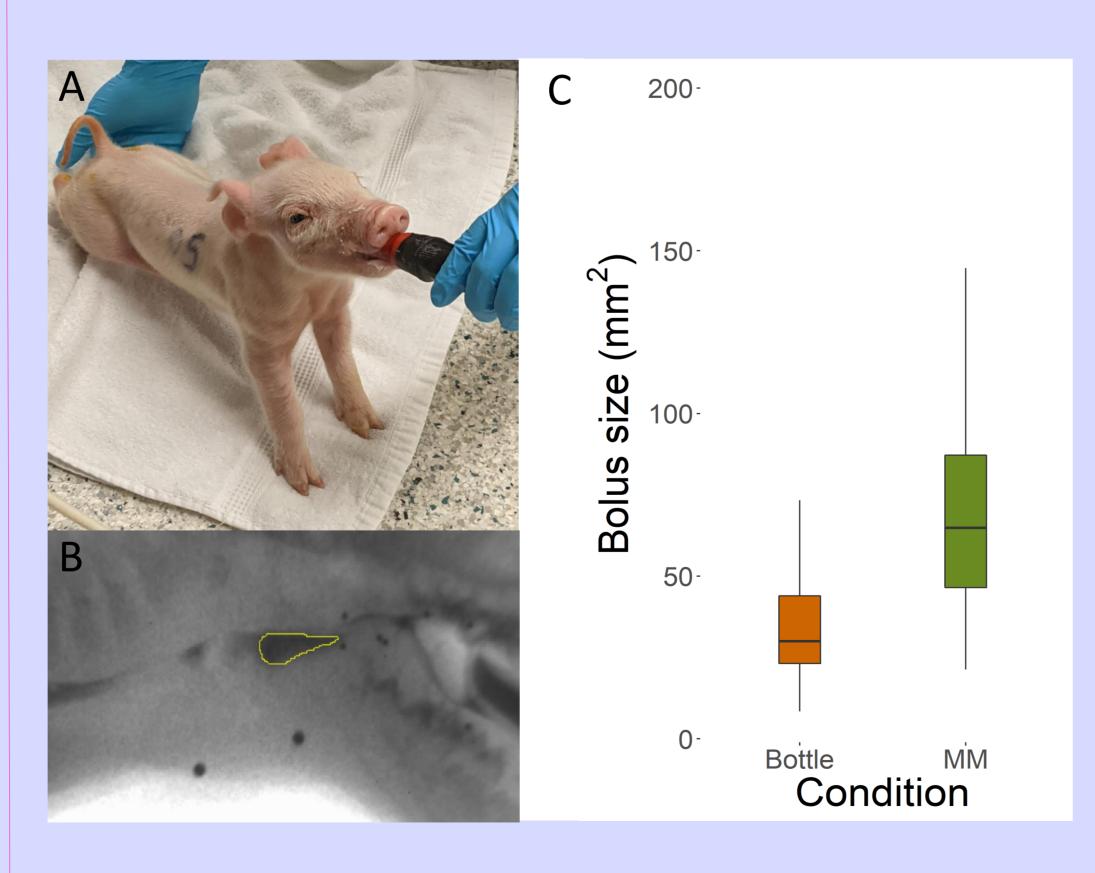
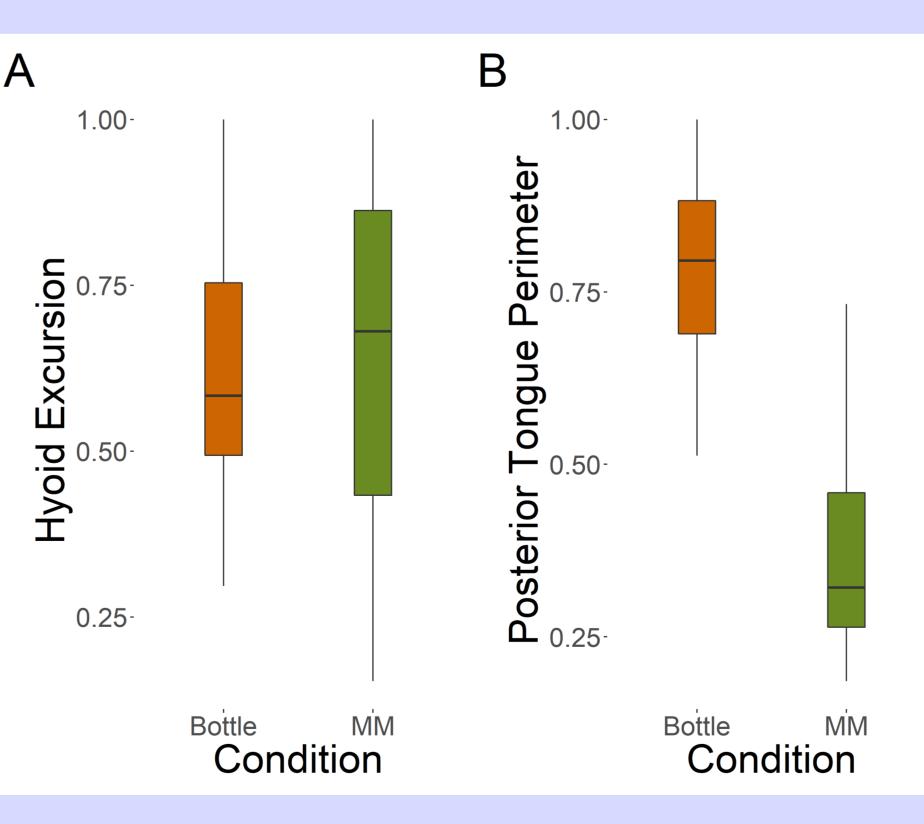


Figure 3. Automated delivery during infant pig feeding (A). The outline of a bolus in the valleculae used in measuring bolus size (B). Boxplot (C) showing automated delivery resulted in increased boluses.

Figure 4. Boxplots showing differences in scaled hyoid excursion (A) and posterior tongue perimeter during swallowing (B). Automated feeding did not alter hyoid excursion, but did result in decreased posterior tongue perimeter.

Figure 2. Boxplots displaying differences in scaled anterior tongue dorsal ventral (A) and anteroposterior movement (B). Automated milk delivery resulted in less DV movement and more AP movement.

Hyoid excursion was no different between conditions (Fig. 4A), but posterior tongue perimeter was larger when bottle feeding (Fig. 4B).



- feeding³.



We thank the staff at the NEOMED Comparative Medicine Unit (CMU) for their assistance with animal care, as well as C. Poletto at Neurovation for his assistance in the design and construction of the automated feeding device. We would also like to thank NIH NICHD for funding (Grant R01HD096881 to RZG).

- 322-330.
- 19: 147-154.



Eunice Kennedy Shriver National Institute of Child Health and Human Development

pregnancies. Healthy children. Healthy and optimal lives.

Conclusions

• Use of an automated milk delivery system reduced sucking kinematics, which has downstream effects on feeding performance.

• Understanding the sensorimotor integration with infant feeding will improve our understanding of the physiology of infant

• A better understanding of the physiology of feeding will improve infant health for compromised populations.

Acknowledgements

References

1.German RZ, Crompton AW, Levitch LC, and Thexton AJ. 1992. The Mechanism of Suckling in Two Species of Infant Mammal: Miniature Pigs and Long-Tailed Macaques. JEZ 261:

2.German RZ, Crompton AW, Owerkowicz T, and Thexton AJ. 2004. Volume and Rate of Milk Delivery as Determinants of Swallowing in an Infant Model Animal (Sus scrofa). Dysphagia,

3. Mayerl CJ, Edmonds CE, Catchpole EA, Myrla AM, Gould FDH, Bond LE, Stricklen BM, and German RZ. Sucking versus swallowing coordination, integration, and performance in preterm and term infants. J. Appl. Phys. 129: 1383-1392.





Ped Stee

